

## DeepBlue Sensor



## Video Image Analyzer

Urban Mobility Detection based on deep learning and object recognition using a digital camera.

Vehicle classification, bicycle and pedestrian counting, all in one single device

Per-vehicle information, Speed detection, Occupancy, Headway

1-camera or 4- camera solution, 8, 16, 32 or 64 outputs/inputs option available

Online web based applications, Ethernet, Field proven, easy set-up and configuration, multi-lane

Cost effective, Self-diagnostics, Autonomous

Per-vehicle and aggregated data available via Web Services

With our dedication to continuous development the specifications are subject to change. To verify the current information please visit www.deepbluesensor.com





# DeepBlue

### Sensor





#### **POWER SUPPLY**

19V-24DC
DeepBlue VIA (Video Image Analyzer)
typical 17 W
Camera typical 3W (camera dependant)

#### **VIDEO PROCESSING**

NVIDIA Xavier NX / NANO 64-bit Cuad-core ARM A57 128-Core NVIDIA Maxwell GPU 1-camera or 4-camera solution

#### **COMMUNICATIONS**

Ethernet
VPN Remote Sensor Access
4 Digital outputs
Optional extra IO board

#### **OPERATIONS**

Linux based OS

#### **ENVIRONMENTAL**

-25°C to +70°C with fan (easy-mount) -25°C to +60°C without fan Mounting for cabinet integration

#### **DIMENSIONS & WEIGHT**

H x W x L 180 mm x 136 mm x 61,1 mm 1.3 kg

#### **DETECTION**

Object recognition

Up to 20 detection zones per camera

Shadow immunity using Deep learning models +95% counting accuracy in daylight clear weather

- 135 /0 Counting accuracy in daying it clear weather
- +95% classification accuracy for two classes
- +95% speed detection accuracy

#### **REGULATORY**

RoHS Compliant, CE, FCC, IC certified

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